

APPLICATION OF QUANTUM HAMILTON EQUATIONS

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Wolfgang Paul¹**

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30th Nov 2017

- Nelson's stochastic mechanics
- Stochastic Mechanics as an optimal control problem
(Derivation of quantum Hamilton equations)
- Numerical algorithm
- Results for stationary problems
 - > Double-well potential
 - > Excited states
 - > Simple multidimensional systems

ANALOGY BETWEEN CLASSICAL AND QUANTUM MECHANICS

Classical mechanics

Hamilton principle

$$S[x] = \int_0^T \left\{ \frac{1}{2} m v(t)^2 - V(x, t) \right\} dt$$

Hamilton-Jacobi equation

$$\partial_t S(x, t) - V(x, t) - \frac{1}{2m} (\nabla_x S(x, t))^2 = 0$$

Newton's equations

$$\dot{x}(t) = v(t), \quad m a(t) = F = -\nabla_x V(x, t)$$

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Quantum Hamilton principle

$$J[x] = \mathbb{E} \left[\int_0^T \left\{ \frac{1}{2} m (\dot{v} - i u)^2 - V(x, t) \right\} dt + \Phi_0(x_0) \right]$$

M. Pavon, J. Math. Phys., 36: 6774-6800, 1995

Schrödinger equation

$$i \hbar \partial_t \Psi(x, t) = \left[-\frac{\hbar^2}{2m} \Delta + V(x, t) \right] \Psi(x, t)$$

$$v(x, t) = \frac{\nabla_x \Im \ln \Psi}{m}, \quad u(x, t) = \frac{\hbar}{m} \nabla_x \Re \ln \Psi$$

Kinematic equations

$$dx(t) = [v(x, t) + u(x, t)] dt + \sqrt{\frac{\hbar}{m}} dW_f(t), \quad \mathbb{E}[ma(t)] = F$$

$$dx(t) = [v(x, t) - u(x, t)] dt + \sqrt{\frac{\hbar}{m}} dW_b(t)$$

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FORWARD BACKWARD STOCHASTIC DIFFERENTIAL EQUATIONS (FBSDE)

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Nelson: particles subjected to conservative Brownian motion (diffusion process) where **interaction with the environment** can not be neglected

$$\text{diffusion coefficient} \quad \sigma^2 = \frac{\hbar}{m} \quad \mathbb{E}[ma] = -\partial_x V(x, t)$$

- equivalent to Schrödinger equation, if wavefunction has the form

$$\psi(x, t) = \exp \{ R(x, t) + i S(x, t) \}$$

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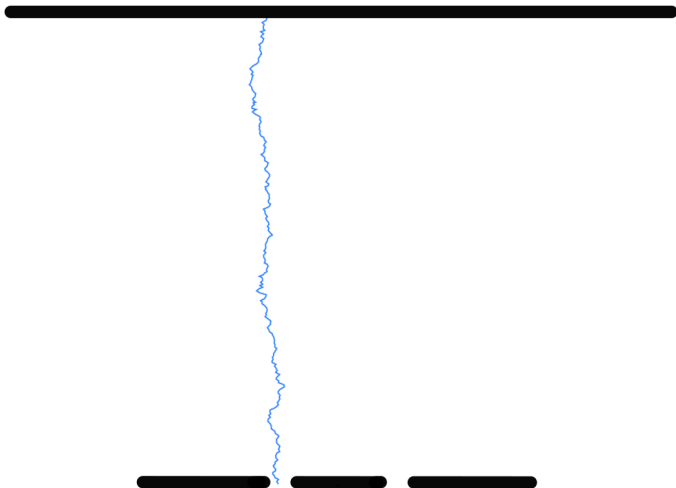
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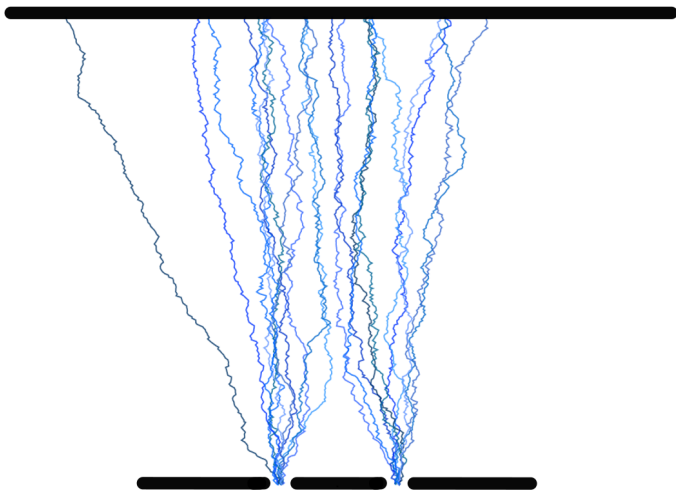
EXAMPLE: DOUBLE SLIT (ELECTRONS)

with known v and $u \rightarrow$ create realizations of quantum point particles
 $N = 1$



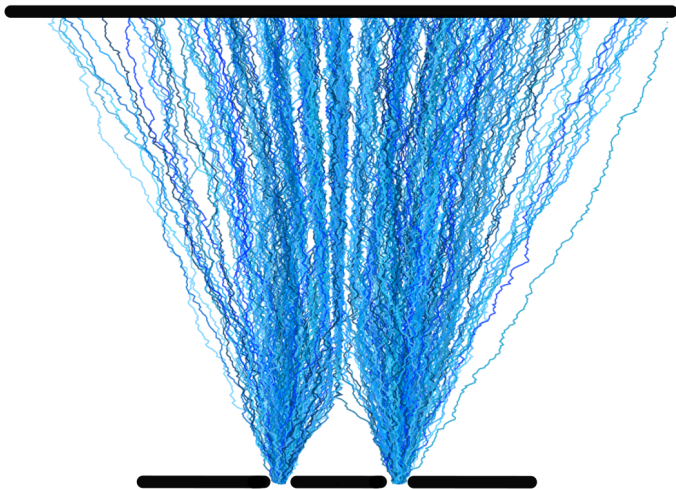
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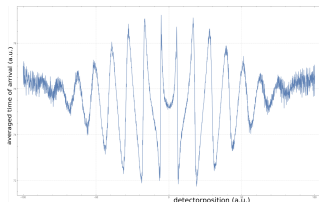
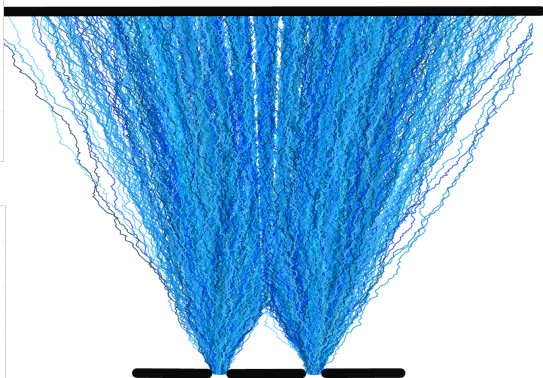
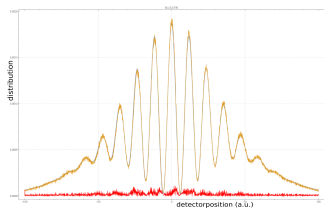
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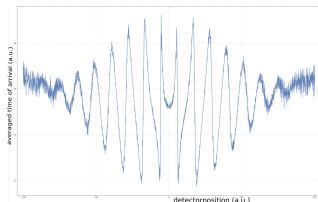
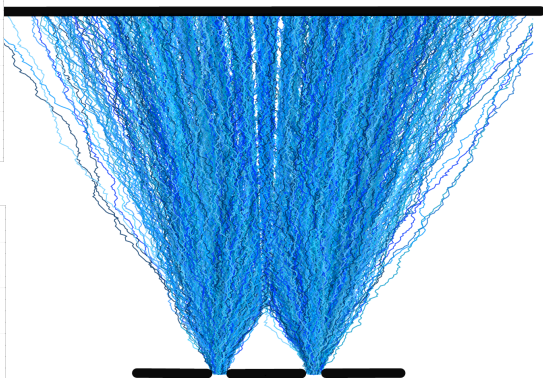
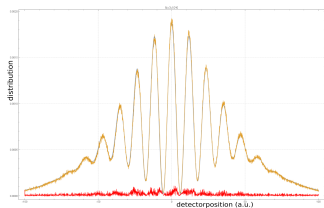
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problem: solution of Schrödinger equation is needed to get the velocities v , u

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STOCHASTIC OPTIMAL CONTROL PROBLEM

Hamilton's principle: extremize action functional w. r. t. x

$$J[x] = \int_0^T \mathcal{L}(t, x(t), \dot{x}(t)) dt \quad \text{Lagrangian } \mathcal{L} = T - V$$

Quantum Hamilton principle as stoch. optimal control problem [3, 1]:

- maximization of cost function J with \mathcal{L} as (stochastic) Lagrange function

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- subject to the constraint (controlled equation)

$$dx(t) = v_q(t, x(t))dt + \frac{1}{2}\sigma((1+i)dW(t) + (1-i)W_*(t)), \quad x(0) = x_0$$

- v_q is the quantum velocity $v_q = v - iu$ and the optimal feedback control to $x(t)$

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$$dx(t) = v(x, t)dt, \quad mdv = -\partial_x V(x, t)dt$$

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TOWARDS A NUMERICAL SOLUTION

→ problem: four unknown stochastic processes x, v, u, q

- consider stationary case $v \equiv 0$, all information is stored in u , e. g.

$$\rho(x) = \exp \left[\frac{2}{\sigma^2} \int_{\mathcal{C}} u(x') \cdot dx' \right]$$

- discretize time axis, e. g. using Euler-Mayurama Scheme

$$\begin{aligned} x^\pi(t_{i+1}) &= x^\pi(t_i) + u^\pi(x^\pi(t_i))\Delta t + \sigma\Delta W(t_i) \\ u^\pi(x^\pi(t_i)) &= u(x^\pi(t_{i+1})) - \partial_x V(x^\pi(t_i))\Delta t - q^\pi(t_i)\Delta W_*(t_i) \end{aligned}$$

- due to Markov property the backward equation can be calculated with the help of **conditional expectation**

$$u^\pi(x^\pi(t_i)) = \mathbb{E}[u^\pi(x^\pi(t_{i+1})) | x^\pi(t_i)] - \partial_x V(x^\pi(t_i))\Delta t$$

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ITERATION SCHEME

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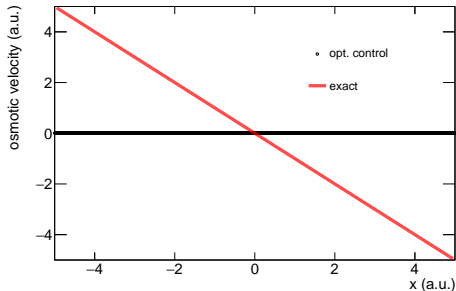
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- 2 integrate u backward in time
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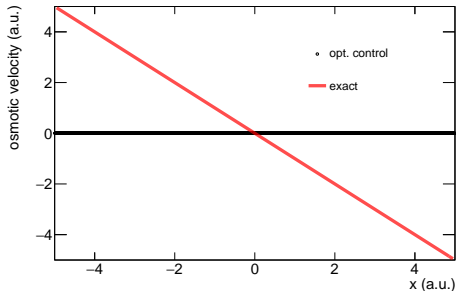
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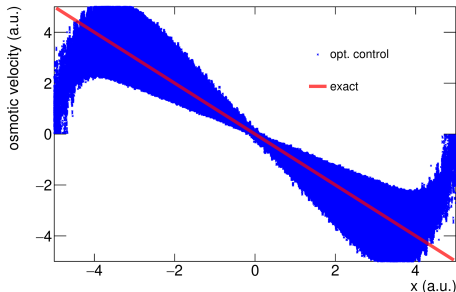
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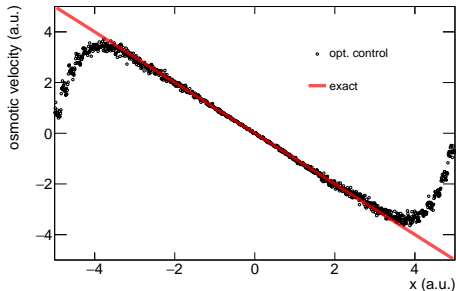
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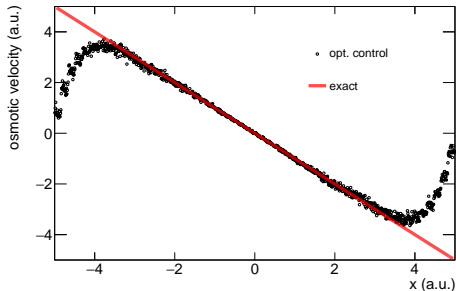
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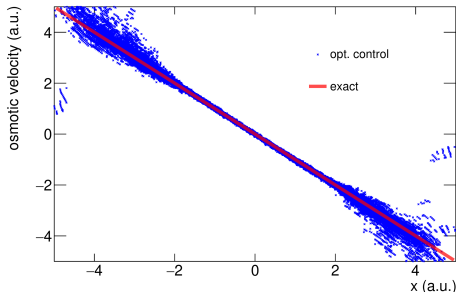
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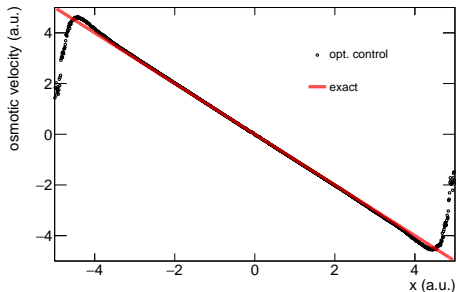
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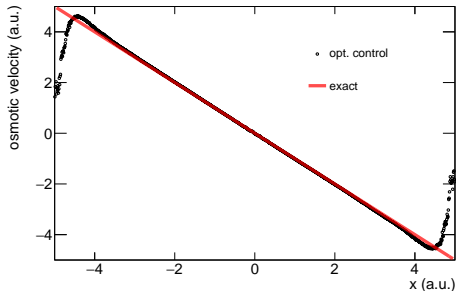
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- 1 use u to generate N paths with n_t steps
- 2 integrate u backward in time
- 3 average $u(x(t_i))$ over intervals $\rightarrow u(x) = \langle u(x(t_i)) \rangle_{\text{cube}}$
- 4 go to 1

1D harmonic oscillator

$$V(x) = \frac{1}{2} m \omega^2 x^2$$

$$x^\pi(t_{i+1}) = x^\pi(t_i) + u^\pi(x^\pi(t_i))\Delta t + \sigma \Delta W(t_i)$$

$$u^\pi(x^\pi(t_i)) = \mathbb{E}[u^\pi(x^\pi(t_{i+1})) | x^\pi(t_i)] - \partial_x V(x^\pi(t_i))\Delta t$$



ITERATION SCHEME

ITERATION SCHEME FOR u

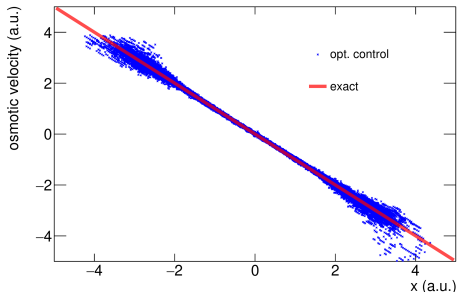
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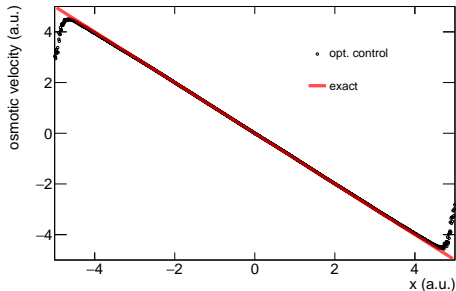
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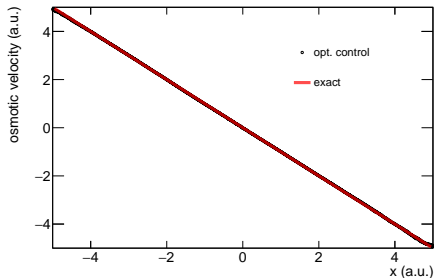
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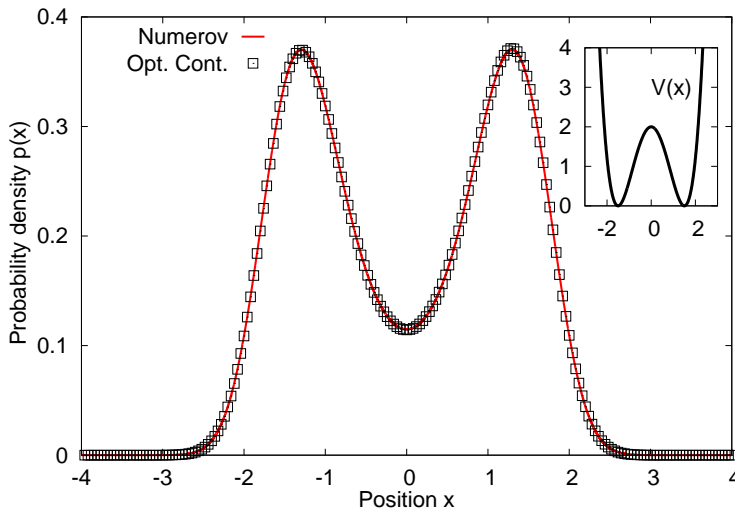
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$u(x)$ after 50 iterations

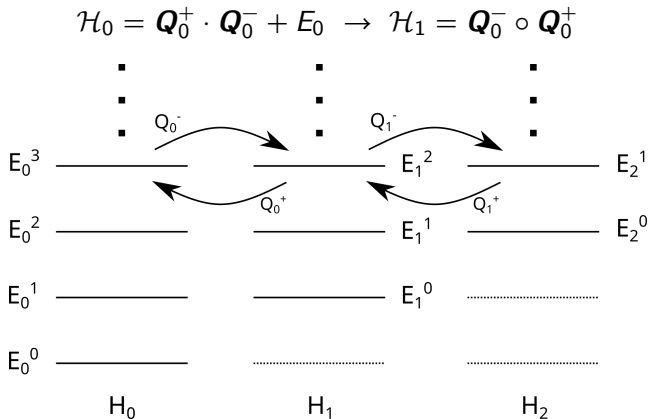


DOUBLE WELL: GROUND STATE

$$V(x) = \frac{V_0}{a^4}(x^2 - a^2)^2 \quad V_0 = 2, \quad a = 1.5$$



SUSY IN STOCHASTIC MECHANICS

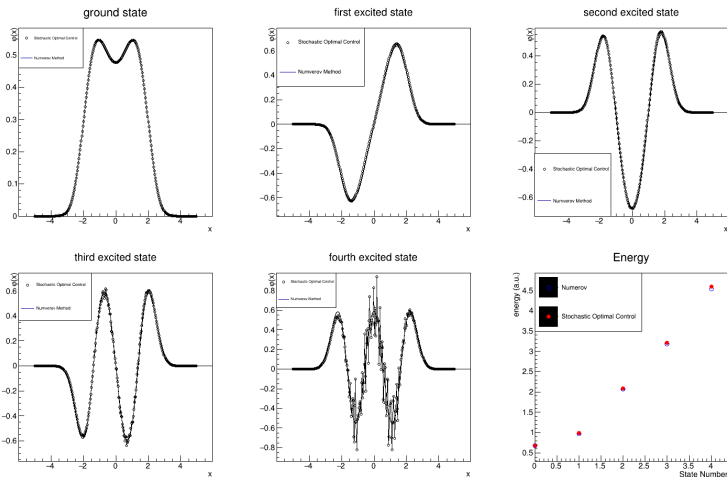


e. g. for the Hamiltonian \mathcal{H}_i in cartesian coordinates

$$\mathbf{Q}_i^\pm = \mp \nabla - \mathbf{u}_i$$

DOUBLE WELL: EXCITED STATES

$$V(x) = \frac{V_0}{4}(x^2 - a^2)^2 \quad V_0 = 1, \quad a = 1.5$$

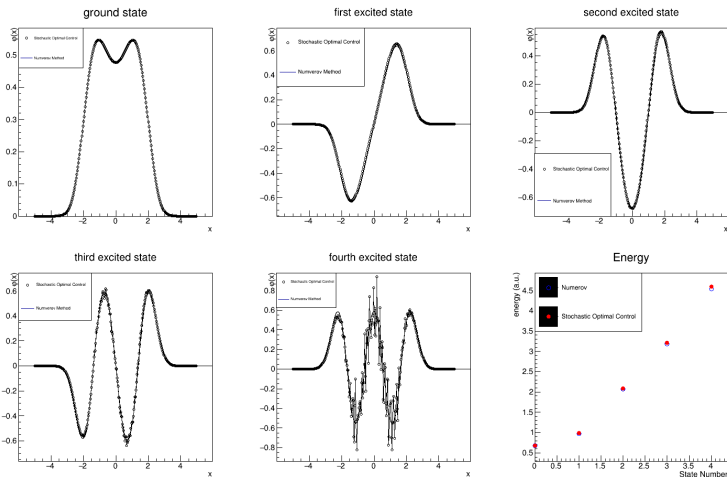


- Tunnel splitting is given by the mean first passage time
- Perturbation theory prediction for the splitting is not correct

} → Poster

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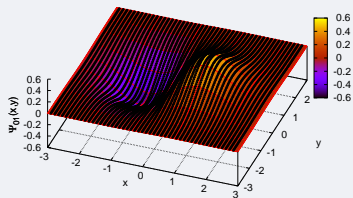


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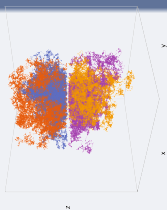
} → Poster

HIGHER DIMENSIONAL SYSTEMS

2D ISOTROPIC HARMONIC OSCILLATOR



3D HYDROGEN ATOM

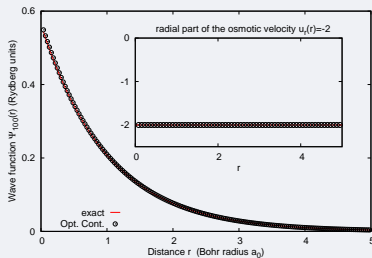


SPHERICAL PROBLEMS

$$dr = \left(u_r + \frac{\sigma^2}{r} \right) dt + \sigma dW$$

$$\mu du_r = \frac{1}{r^2} (\hbar u_r + \partial_r V(r)) dt + (qdW_*)_r$$

hydrogen atom






SUMMARY

- Derivation of kinematic and dynamic equations for non-relativistic quantum system → **quantum Hamilton equations**
- Numerical algorithm to solve these stochastic equations in the stationary case without using the Schrödinger equation
- Solution to (simple) problems in higher dimensions
- Determination of all excited eigenstates of the Schrödinger equation

Future work

- > Solving non-stationary problems numerically
- > Extending to relativistic particles and spin

LITERATURE I

-  J. Köppe, W. Grecksch, and W. Paul.
Derivation and application of quantum hamilton equations of motion.
Annalen der Physik, 529(3):1600251–n/a, 2017.
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-  Edward Nelson.
Derivation of the schrödinger equation from newtonian mechanics.
Physical Review, 150(4):1079, 1966.
-  Michele Pavon.
Hamilton's principle in stochastic mechanics.
Journal of Mathematical Physics, 36(12):6774–6800, 1995.

Thank you for your attention!

NELSON'S STOCHASTIC MECHANICS

E. NELSON, *Derivation of the Schrödinger equation from Newtonian mechanics. Phys. Rev.* 150, 1079 (1966)

FORWARD BACKWARD STOCHASTIC DIFFERENTIAL EQUATIONS (FBSDE)

$$dx(t) = [v(t, x(t)) + u(t, x(t))]dt + \sigma dW(t) , \quad x(t_0) = x_0$$

$$dx(t) = [v(t, x(t)) - u(t, x(t))]dt + \sigma dW_*(t) , \quad x(T) = x_T$$

where:

- $x(t) = x(t, \omega)$ is a stochastic process in $\mathbb{R}^{n \cdot d}$
- $x(t)$ is connected to a probability distribution ρ satisfying a forward and backward Fokker-Planck equation
- $W(t)$ is a $n \cdot d$ dimensional Wiener processes
- current velocity $v = \sigma^2 \nabla S(t, x(t))$
- $\mathbb{E}[v] = \langle \hat{p} \rangle_\psi$
- osmotic velocity $u = \sigma^2 \nabla R(t, x(t)) = \sigma^2 \nabla \ln \rho(t, x(t))$
- $\mathbb{E}[u] = 0$ and $\mathbb{E}[v^2 + u^2] = \langle (\Delta \hat{p}/m)^2 \rangle_\psi$