

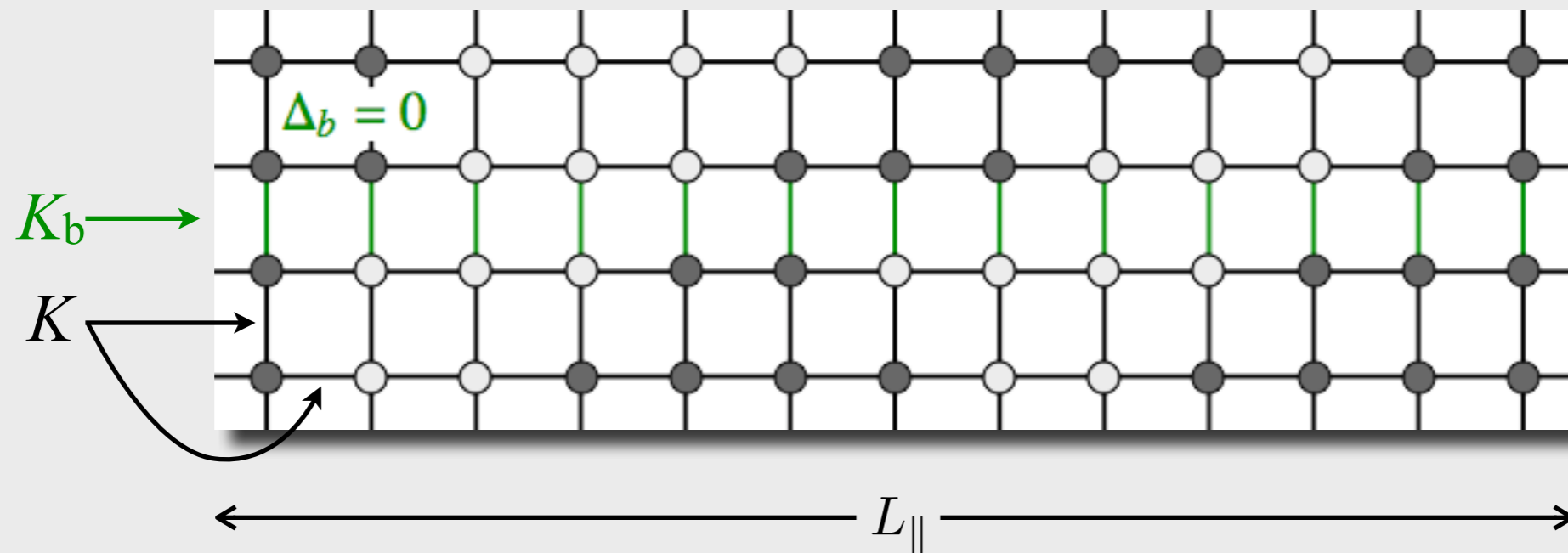
Non-equilibrium phase transition in an exactly solvable driven Ising model with friction

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Fluctuation induced friction at surfaces



- Time-dependent Hamiltonian

$$\beta = 1/k_B T, K = \beta J$$

- $\Delta_b(t) = vt$

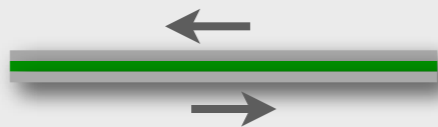
- $v = 1 \hat{=} 1 \text{ cm/s}$

$$a_0 \approx 10^{-10} \text{ m}, t_0 \approx 10^{-8} \text{ s}$$

$$\beta \mathcal{H}(t) = -K \sum_{\langle ij \rangle} \sigma_i \sigma_j - K_b \sum_{\langle ij \rangle_b(t)} \sigma_i \sigma_j$$

Geometries for surface friction

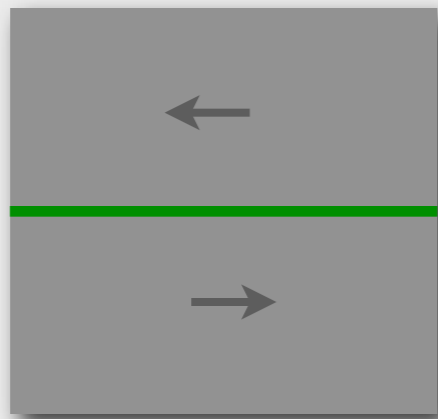
$1d$



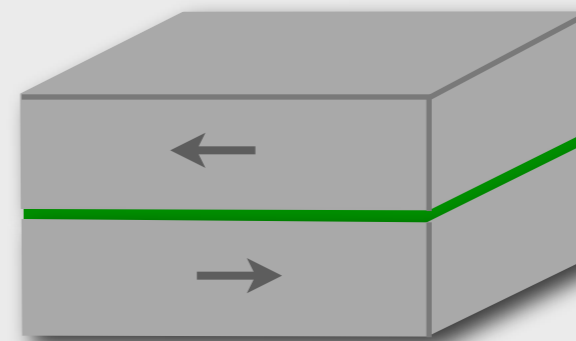
$2d$



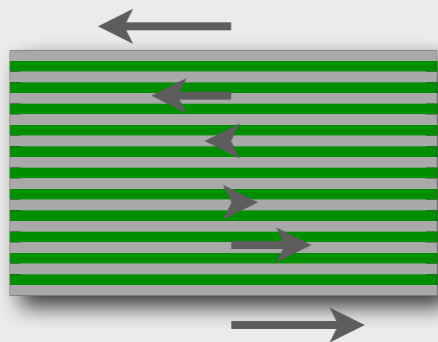
$2d_b$



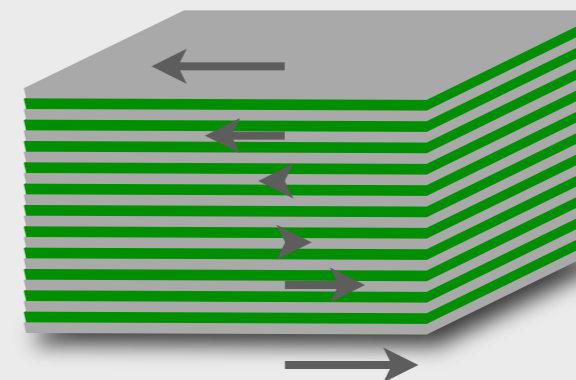
$3d_b$



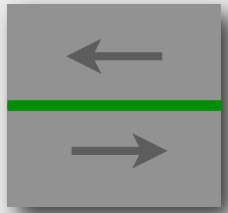
$1+1d$



$2+1d$



Non-equilibrium quantities: Monte Carlo results



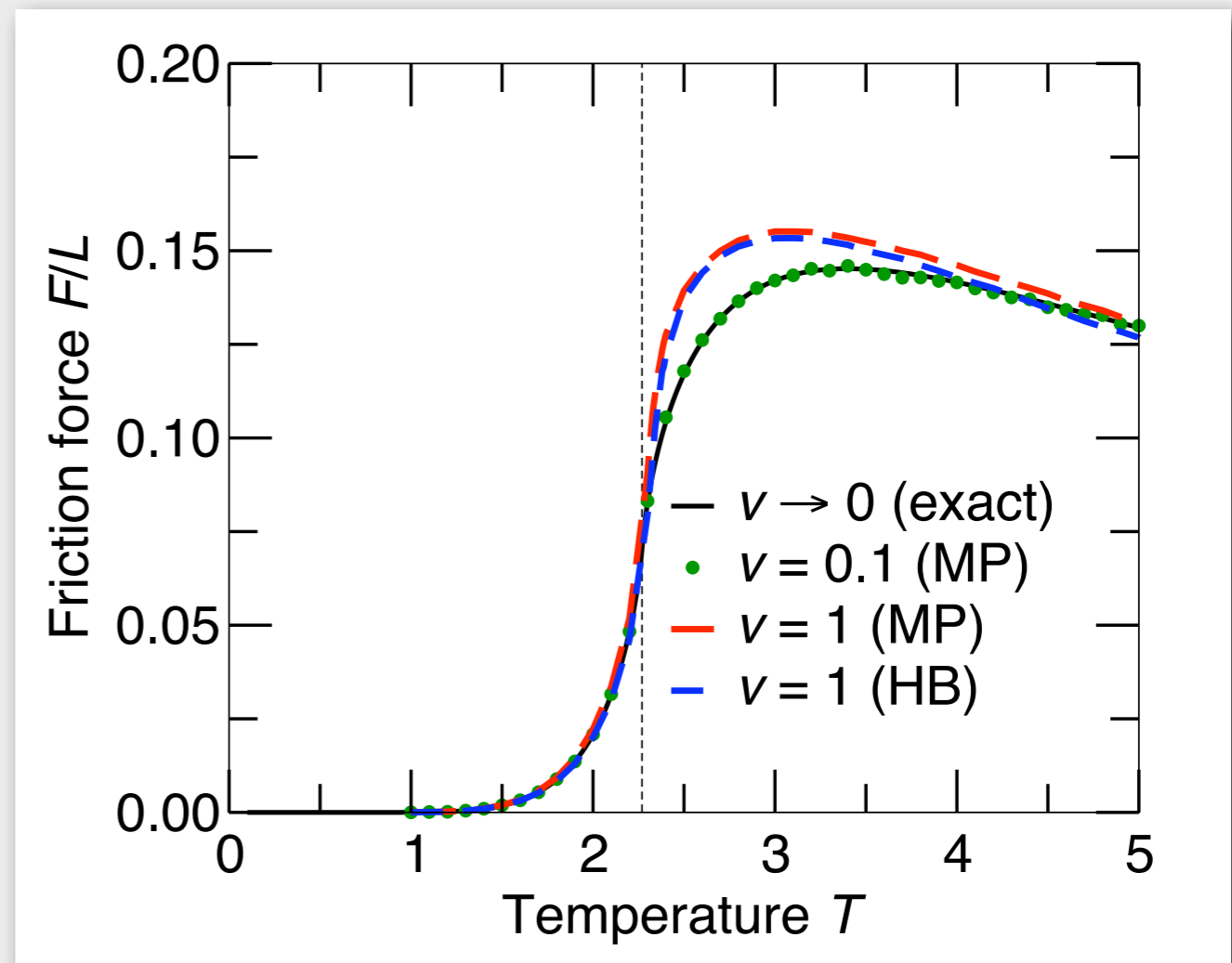
- Energy dissipation rate

$$P(v) = \frac{\langle \Delta E_b \rangle}{\Delta t}$$

- Friction force

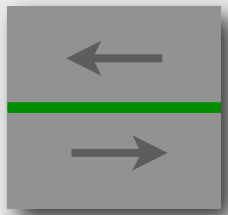
$$F(v) = \frac{P(v)}{v}$$

- Exact solution for small v

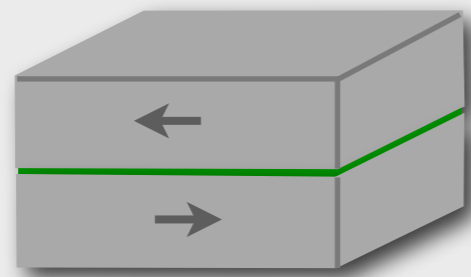


$$\begin{aligned}
 F(v \rightarrow 0) &= \frac{\langle E_b^{(f)} - E_b^{(i)} \rangle}{\Delta s} = -LJ_b \left(\langle \langle \text{diag}_1 \rangle \rangle_0 - \langle \langle \text{diag}_2 \rangle \rangle_0 \right) \\
 &= -LJ_b \left(\langle \sigma_{0,0} \sigma_{1,1} \rangle_0 - \langle \sigma_{0,0} \sigma_{0,1} \rangle_0 \right)
 \end{aligned}$$

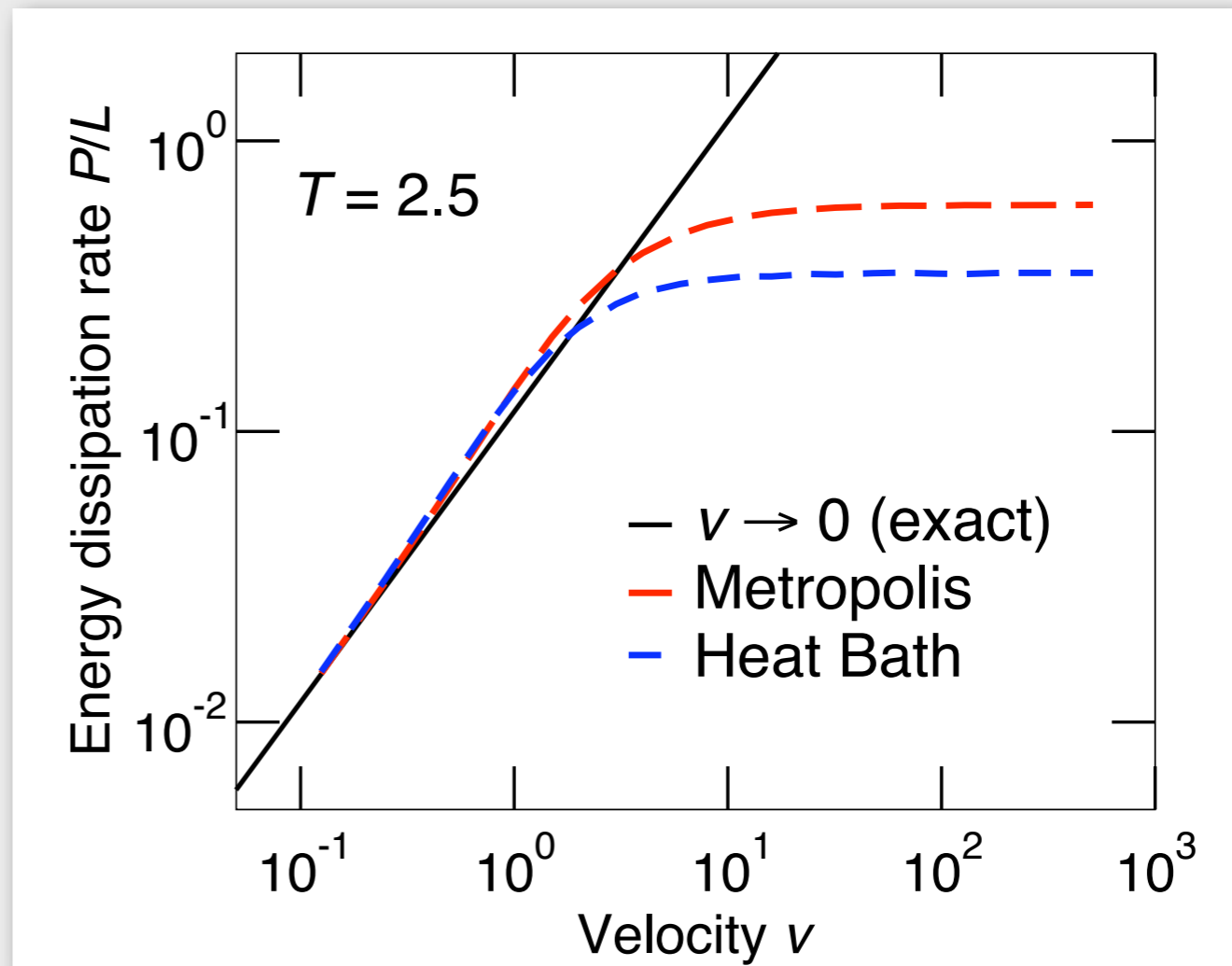
Influence of finite driving velocity v



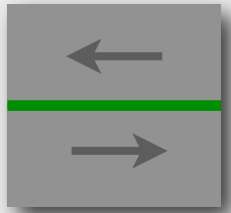
- Dissipation P saturates at high velocities $v \gg 1$
- Quantities depend on Monte Carlo algorithm
- $3d_b$ case (ideal contact):



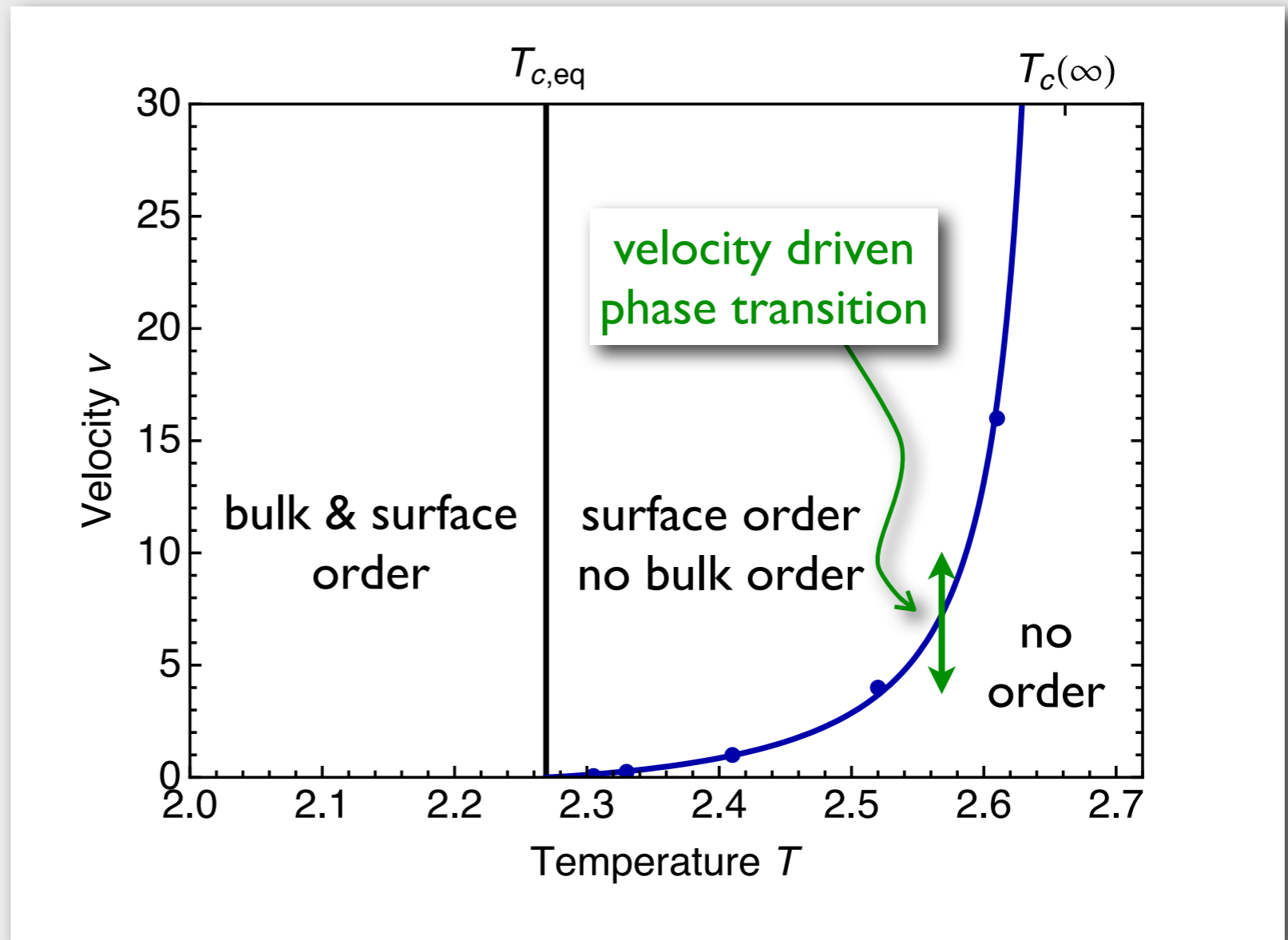
$$P(v \gg 1) \approx 100 \text{ Wcm}^{-2}$$



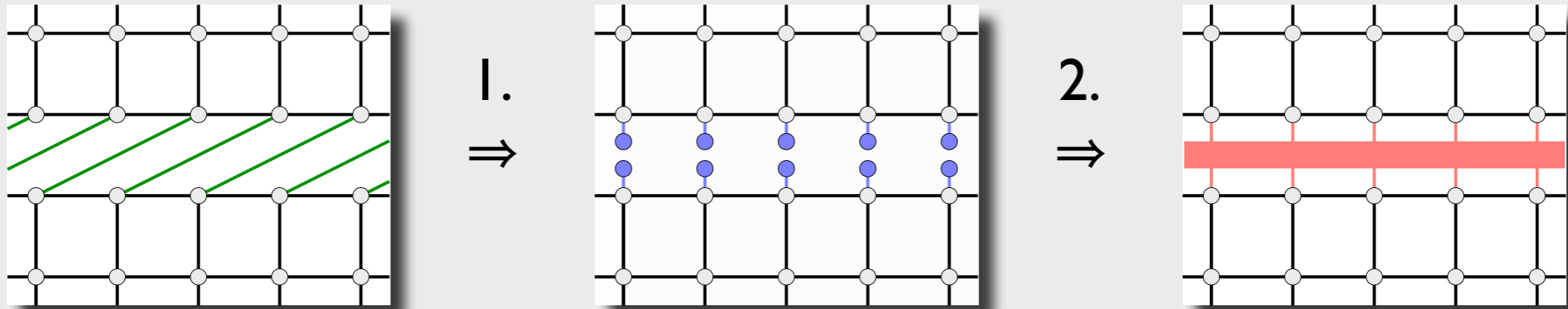
The phase diagram



- T_c depends on velocity v
- 3 phases:
 - bulk order
 - surface order
 - no order
- Velocity driven surface phase transition



High velocities: Exact solution in 3 steps



0. Start with driven system

1. Map boundary couplings K_b to fluctuating fields μ_i with average $\langle \mu_i \rangle = m_b$

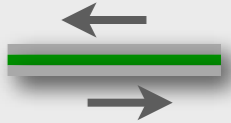
2. Replace fluctuating fields μ_i with static field $h_b(m_b)$

$$\tanh h_b = m_b \tanh K_b$$

3. Solve self-consistency condition

$$m_{b,\text{eq}}(T, h_b(m_b)) = m_b \Rightarrow m_b(T)$$

Application to 1d model at high velocities



- Solution of equilibrium model

$$m_{\text{eq}}(K, h) = \frac{\sinh h}{\sqrt{e^{-4K} + \sinh^2 h}}$$

$$\chi_{\text{eq}}^{(0)}(K) = e^{2K}$$

- Critical point T_c :

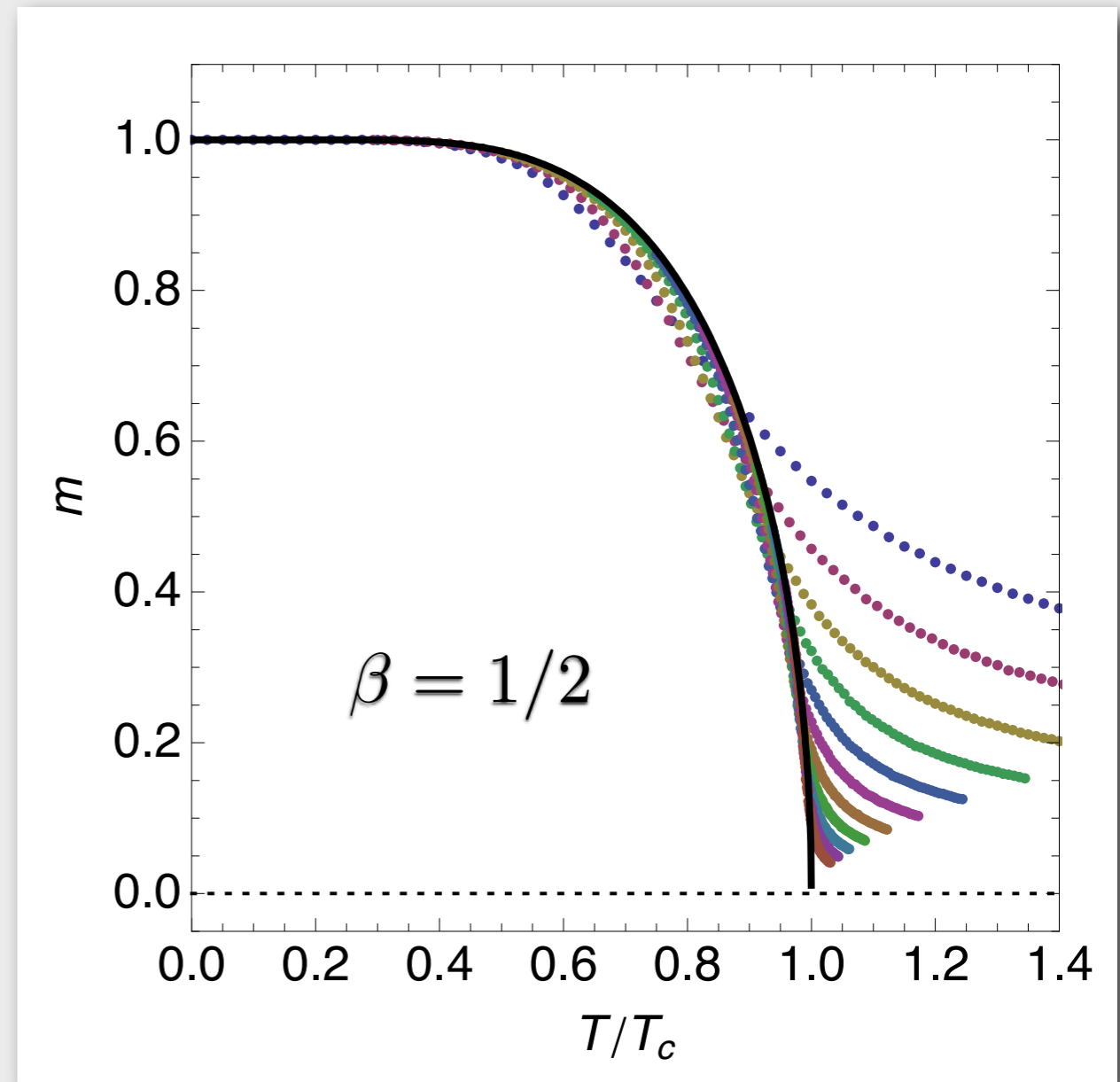
$$\chi_{\text{eq}}^{(0)}(K_c) \tanh K_{b,c} \stackrel{!}{=} 1$$

$$T_c = 2 / \log(\sqrt{2} + 1) = 2.26918\dots$$

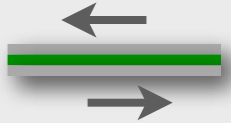
- Order parameter m :

$$m(K, K_b) = \sqrt{\frac{\cosh 2K_b - \coth 2K}{\cosh 2K_b - 1}}$$

- **Note:** Identical to surface magnetization of $2d$ Ising model



Other quantities in $1d$

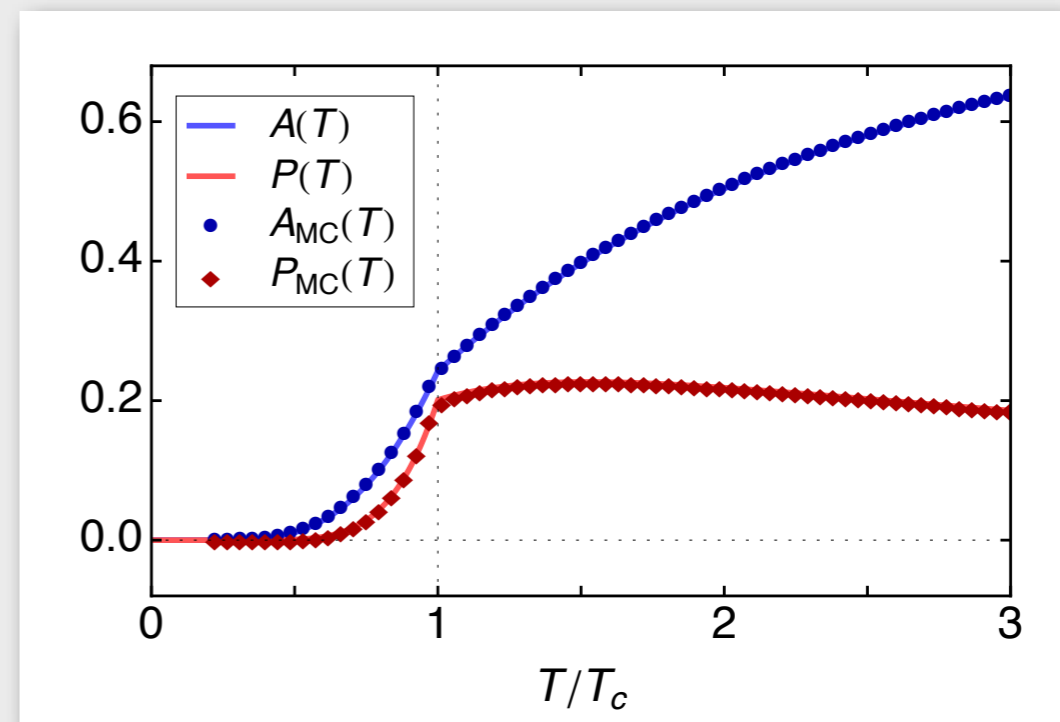
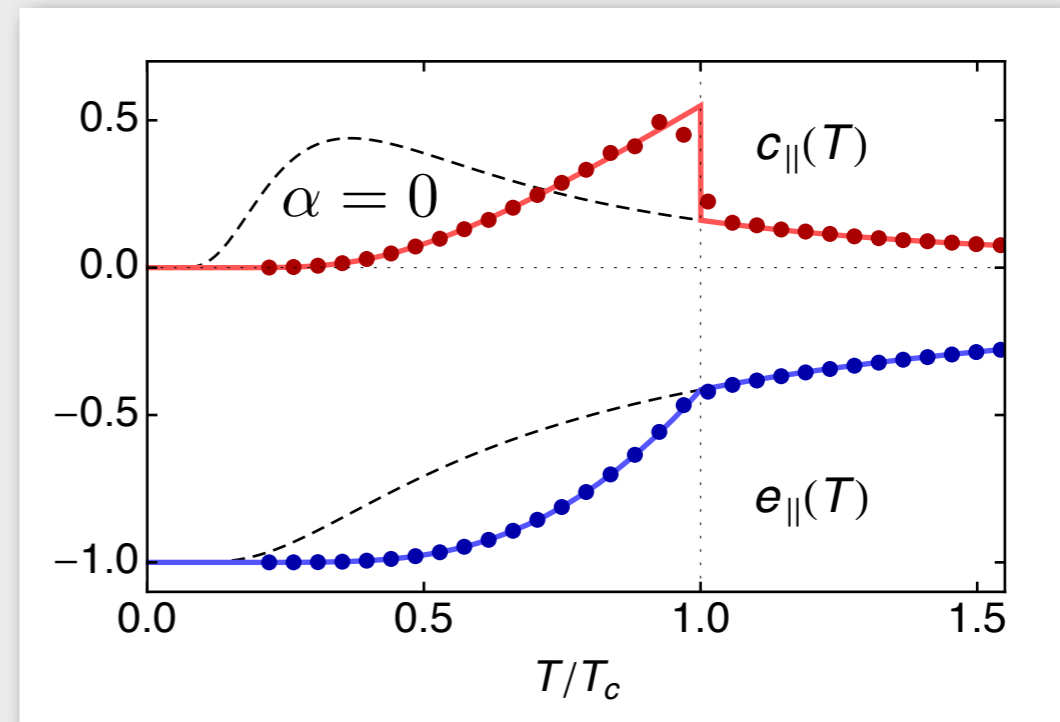


● Static properties:

- internal energy $e_{\parallel}(T)$
- specific heat $c_{\parallel}(T)$
- correlation functions $G(r)$
- ...

● Dynamic properties:

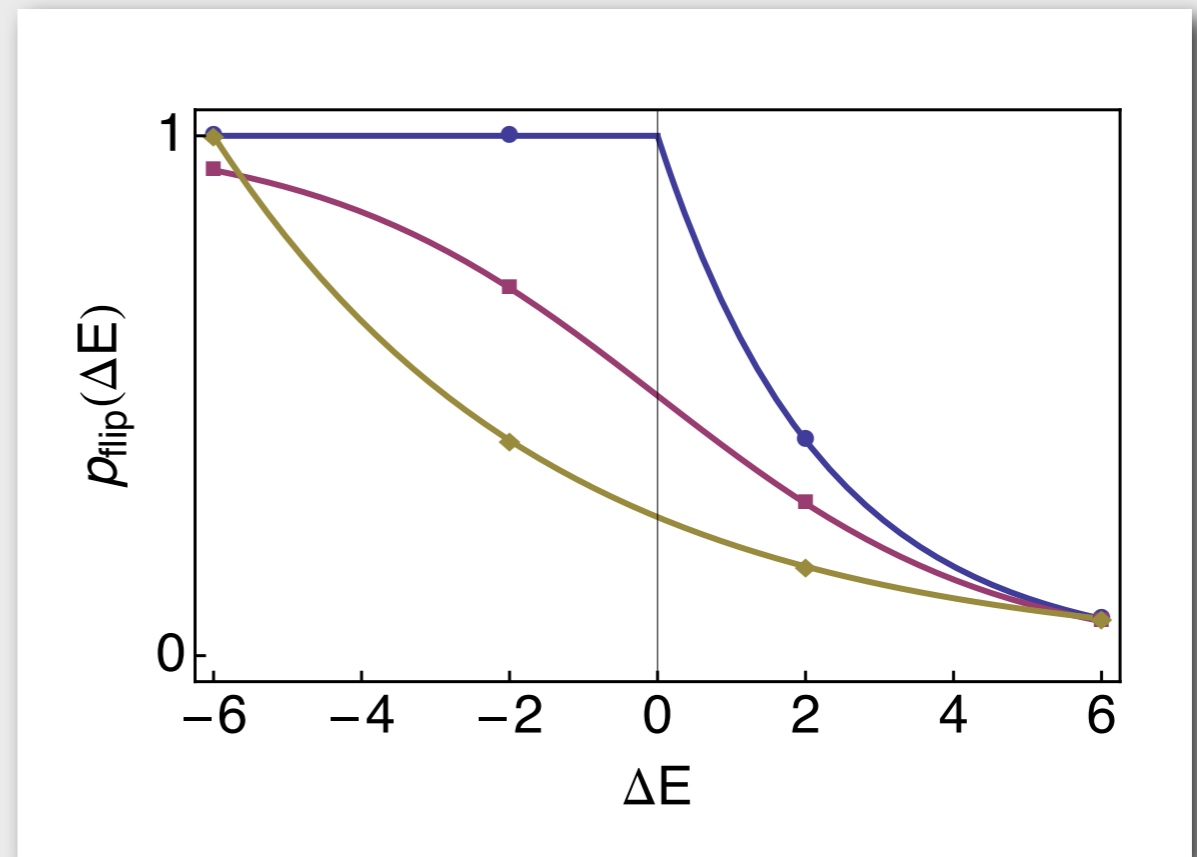
- spin flip acceptance rate $A(T)$
- energy dissipation rate $P(T)$



An integrable Monte Carlo algorithm

- Critical temperature T_c depends on MC algorithm
- Example:
1d case with $J_b = J = 1$

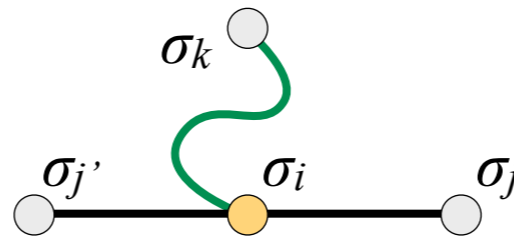
Acceptance rate $A = \langle p_{\text{flip}} \rangle$



Metropolis	$p_{\text{flip}}^{\text{MP}}(\Delta E) = \min(1, e^{-\beta \Delta E})$	$T_c^{\text{MP}} = 1.910(2)$	$A_c^{\text{MP}} = 0.476(2)$
Heat-Bath	$p_{\text{flip}}^{\text{HB}}(\Delta E) = \frac{1}{1 + e^{\beta \Delta E}}$	$T_c^{\text{HB}} = 2.031(2)$	$A_c^{\text{HB}} = 0.366(2)$
Multiplicative	$p_{\text{flip}}^*(\Delta E) = e^{-\frac{\beta}{2}(\Delta E - \Delta E_{\text{min}})}$	$T_c^* = 2.269(1)$	$A_c^* = 0.242(2)$
Exact solution		$T_c = 2.2692\dots$	$A_c = 0.24264\dots$

An integrable Monte Carlo algorithm

- Consider MC update of boundary spin σ_i



$$\Delta E = \underbrace{2J\sigma_i \sum_{\langle j \rangle} \sigma_j}_{\Delta E_1} + \underbrace{2J_b \sigma_i \sigma_k}_{\Delta E_2}$$

- Usual MC algorithms introduce correlations over boundary: Influence on σ_k depends on σ_j

$$\begin{aligned} \sigma_i = -\sigma_j &\rightarrow \Delta E_1 = -4J \rightarrow p_{\text{flip}} = 1 \\ \sigma_i = +\sigma_j &\rightarrow \Delta E_1 = +4J \rightarrow p_{\text{flip}}(\sigma_k) \end{aligned}$$

- Solution: Use algorithm which
 - fulfills detailed balance
 - is multiplicative

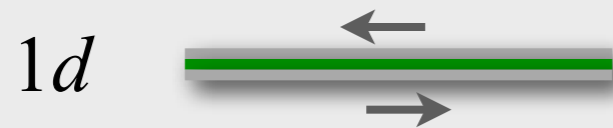
$$\frac{p_{\text{flip}}(\Delta E)}{p_{\text{flip}}(-\Delta E)} = e^{-\beta \Delta E}$$

$$p_{\text{flip}}(\Delta E_1 + \Delta E_2) = p_{\text{flip}}(\Delta E_1) p_{\text{flip}}(\Delta E_2)$$

- Result:

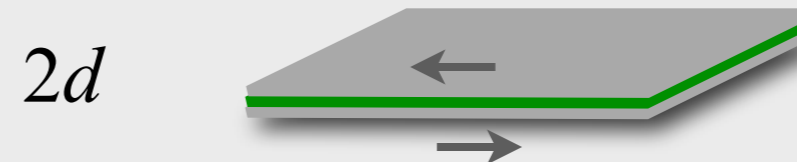
$$p_{\text{flip}}^*(\Delta E) = e^{-\frac{\beta}{2}(\Delta E - \Delta E_{\text{min}})}$$

Results for other geometries (sc lattice)



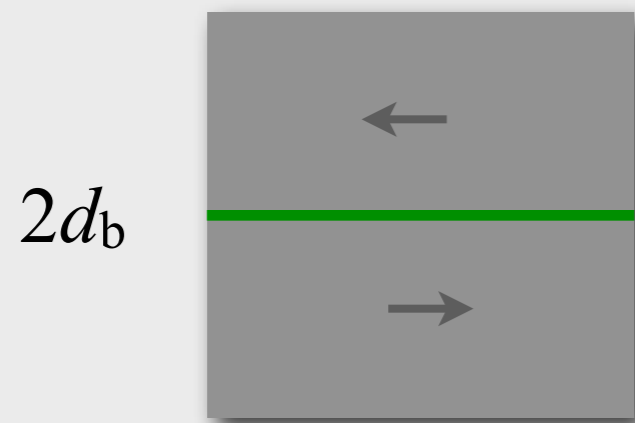
$$\chi_{\text{eq}}^{(1d)}(K_c) \tanh K_{b,c} = 1$$

$$T_c = 2 / \log(\sqrt{2} + 1) = 2.26918\dots$$



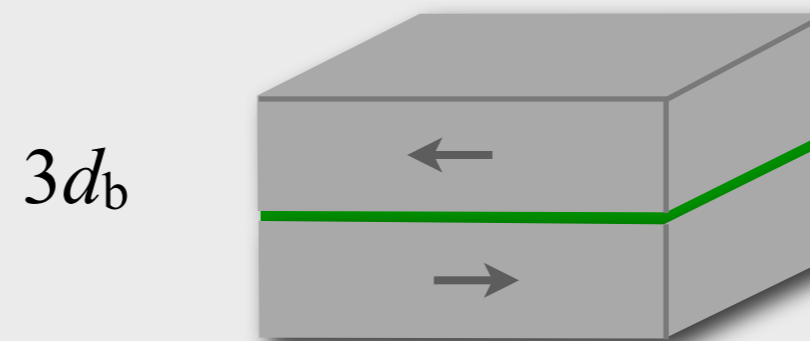
$$\chi_{\text{eq}}^{(2d)}(K_c) \tanh K_{b,c} = 1$$

$$T_c = 4.058782423137980000987775040680\dots$$



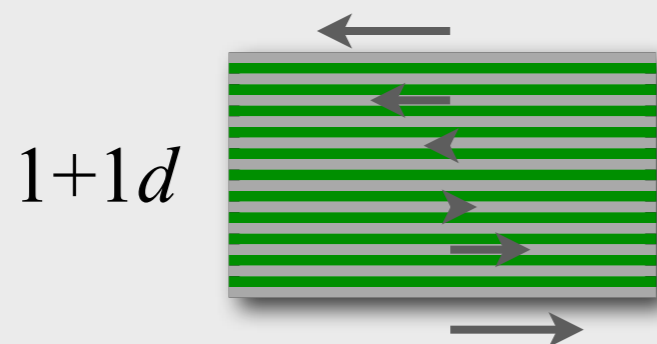
$$\chi_{b,\text{eq}}^{(2d)}(K_c) \tanh K_{b,c} = 1$$

$$T_c = 2.6614725655752\dots$$



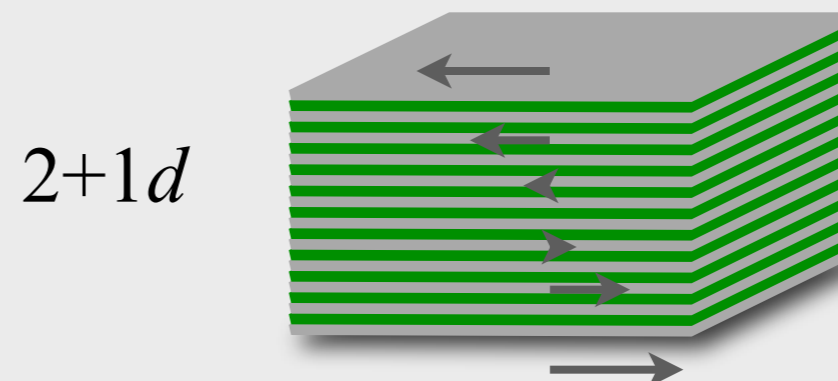
$$\chi_{b,\text{eq}}^{(3d)}(K_c) \tanh K_{b,c} = 1$$

$$T_c = 4.8(1)$$



$$2 \chi_{\text{eq}}^{(1d)}(K_c) \tanh K_{b,c} = 1$$

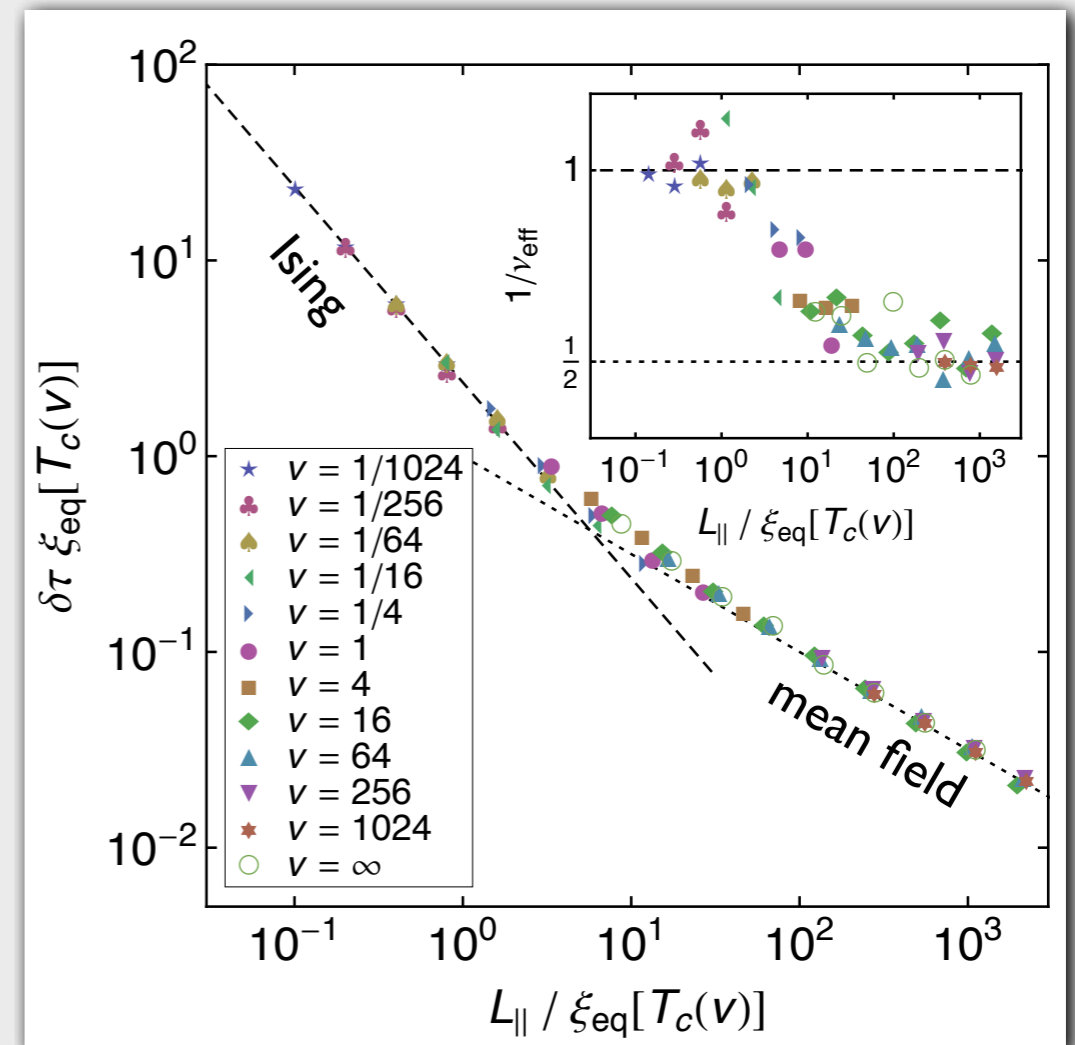
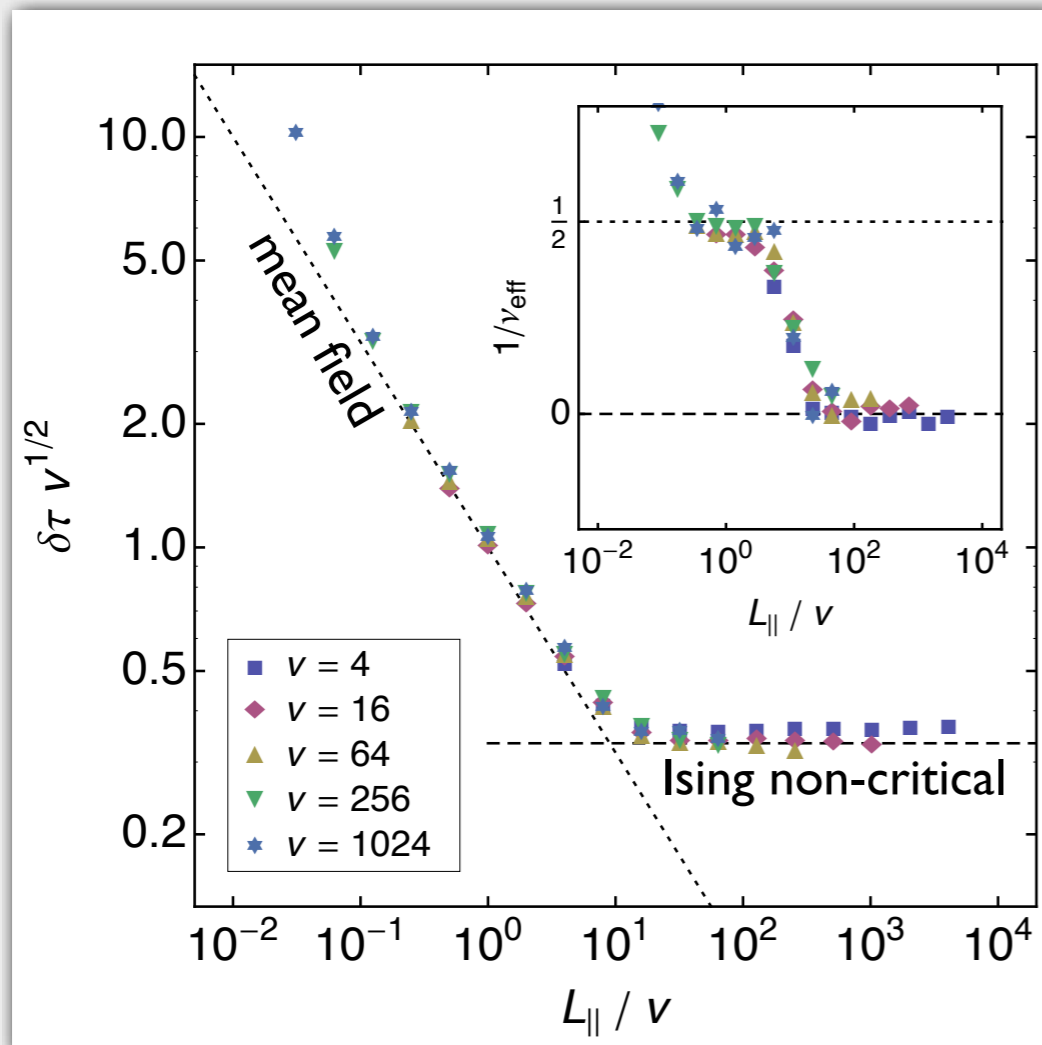
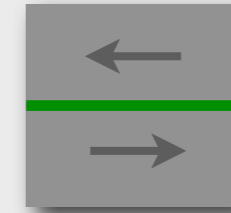
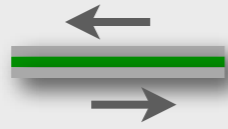
$$T_c = 1 / \log\left(\frac{1}{2} \sqrt{3 + \sqrt{17}}\right) = 3.46591\dots$$



$$2 \chi_{\text{eq}}^{(2d)}(K_c) \tanh K_{b,c} = 1$$

$$T_c = 5.264750414514743550598017203424\dots$$

Finite ν : Cross-over scaling of critical width $\delta\tau$



Conclusions & Outlook

- New contribution to friction from spin correlations
- Driven model shows non-equilibrium phase transition
- Integrable *multiplicative* MC rate for non-equilibrium systems
- Exactly solvable for high velocities ($v \rightarrow \infty$) in many geometries
- Phase transition in mean-field class for $d > 1$ and $v > 0$
- Strongly anisotropic phase transition in sheared systems, with $\theta = v_{\parallel} / v_{\perp} = 3$